Road Vehicle Dynamics Fundamentals Of Modeling And Modelling, Dynamics and Control of Electrified Vehicles provides a systematic overview of EV-related key components, including batteries, electric motors, ultracapacitors and system-level approaches, such as energy management systems, multi-source energy optimization, transmission design and control, braking system control and vehicle dynamics control. In addition, the book covers selected advanced topics, including Smart Grid and connected vehicles. This book shows how EV work, how to design them, how to save energy with them, and how to maintain their safety. The book aims to be an all-in-one reference for readers who are interested in EVs, or those trying to understand its state-of-the-art technologies and future trends. Offers a comprehensive knowledge of the multidisciplinary research related to EVs and a system-level understanding of technologies Provides the state-of-the-art technologies and future trends Covers the fundamentals of EVs and their methodologies Written by successful researchers that show the deep understanding of EVs

Aerodynamics of Road Vehicles details the aerodynamics of passenger cars, commercial vehicles, sports cars, and race cars; their external flow field; as well as their internal flow field. The book, after giving an introduction to automobile aerodynamics and some fundamentals of fluid mechanics, covers topics such as the performance and aerodynamics of different kinds of vehicles, as well as test techniques for their aerodynamics. The book also covers other concepts related to automobiles such as cooling systems and ventilations for vehicles. The text is recommended for mechanical engineers and physicists in the automobile industry who would like to understand more about aerodynamics of motor vehicles and its importance on the field of road safety and automobile production.

Braking of Road Vehicles covers car and commercial vehicle applications and developments from both a theoretical and practical standpoint. Drawing on insights from leading experts from across the automotive industry, experienced industry course leader Andrew Day has developed a new handbook for automotive engineers needing an introduction to or refresh on this complex and critical topic. With coverage broad enough to appeal to general vehicle engineers and detailed enough to inform those with specialist brake interests, Braking of Road Vehicles is a reliable, no-nonsense guide for automotive professionals working within OEMs, suppliers and legislative organizations. Designed to meet the needs of working automotive engineers who require a comprehensive introduction to road vehicle brakes and braking systems. Offers practical, no-nonsense coverage, beginning with the fundamentals and moving on to cover specific technologies, applications and legislative details. Provides all the necessary information for specialists and non-specialists to keep up to date with relevant changes and advances in the area.

An introduction to vehicle dynamics and the fundamentals of mathematical modeling Fundamentals of Vehicle Dynamics and Modeling is a student-focused textbook providing an introduction to vehicle dynamics, and covers the fundamentals of vehicle model development. It illustrates the process for construction of a mathematical model through the application of the equations of motion. The text describes techniques for solution of the model, and demonstrates how to conduct an analysis and interpret the results. A significant portion of the book is devoted to the classical linear dynamic models, and provides a foundation for understanding and predicting vehicle behaviour as a consequence of the design parameters. Modeling the pneumatic tire is also covered, along with methods for solving the suspension kinematics problem, and prediction of acceleration and braking performance. The book introduces the concept of multibody dynamics as applied to vehicles and provides insight into
how large and high fidelity models can be constructed. It includes the development of a method suitable for computer implementation, which can automatically generate and solve the linear equations of motion for large complex models. Key features: ? Accompanied by a website hosting MATLAB® code. ? Supported by the Global Education Delivery channels. Fundamentals of Vehicle Dynamics and Modeling is an ideal textbook for senior undergraduate and graduate courses on vehicle dynamics.

Engineering principles for dynamics vehicles. This book covers the principles and applications of vehicle handling dynamics from an advanced perspective in depth. The methods required to analyze and optimize vehicle handling dynamics are presented, including tire compound dynamics, vehicle planar dynamics, vehicle roll dynamics, full vehicle dynamics, and in-wheel motor vehicle dynamics. The provided vehicle dynamic model is capable of investigating drift, sliding, and other over-limit vehicle maneuvers. This is an ideal book for postgraduate and research students and engineers in mechanical, automotive, transportation, and ground vehicle engineering. Governed by strict regulations and the intricate balance of complex interactions among variables, the application of mechanics to vehicle crashworthiness is not a simple task. It demands a solid understanding of the fundamentals, careful analysis, and practical knowledge of the tools and techniques of that analysis. Vehicle Crash Mechanics sets forth the basic principles of engineering mechanics and applies them to the issue of crashworthiness. The author studies the three primary elements of crashworthiness: vehicle, occupant, and restraint. He illustrates their dynamic interactions through analytical models, experimental methods, and test data from actual crash tests. Parallel development of the analysis of actual test results and the interpretation of mathematical models related to the test provides insight into the parameters and interactions that influence the results. Detailed case studies present real-world crash tests, accidents, and the effectiveness of air bag and crash sensing systems. Design analysis formulas and two- and three-dimensional charts help in visualizing the complex interactions of the design variables. Vehicle crashworthiness is a complex, multifaceted area of study. Vehicle Crash Mechanics clarifies its complexities. The book builds a solid foundation and presents up-to-date techniques needed to meet the ultimate goal of crashworthiness analysis and experimentation: to satisfy and perhaps exceed the safety requirements mandated by law.

This set includes Race Car Vehicle Dynamics, and Race Car Vehicle Dynamics - Problems, Answers and Experiments. Written for the engineer as well as the race car enthusiast, Race Car Vehicle Dynamics includes much information that is not available in any other vehicle dynamics text. Truly comprehensive in its coverage of the fundamental concepts of vehicle dynamics and their application in a racing environment, this book has become the definitive reference on this topic. Although the primary focus is on the race car, the engineering fundamentals detailed are also applicable to passenger car design and engineering. Authors Bill and Doug Milliken have developed many of the original vehicle dynamics theories and principles covered in this book, including the Moment Method, “g-g” Diagram, pair analysis, lap time simulation, and tyre data normalization. The book also includes contributions from other experts in the field. Chapters cover: *The Problem Imposed by Racing *Tire Behavior *Aerodynamic Fundamentals *Vehicle Axis Systems and more. Written for the engineer as well as the race car enthusiast and students, the companion workbook to the original classic book, Race Car Vehicle Dynamics, includes: *Detailed worked solutions to all of the problems *Problems for every chapter in Race Car Vehicle Dynamics, including many new problems *The Race Car Vehicle Dynamics Program Suite (for Windows) with accompanying exercises *Experiments to try with your own vehicle *Educational appendix with additional references and course outlines *Over 90 figures and graphs This workbook is widely used as a college textbook and has been an SAE International best seller since it's introduction in 1995.
Hybrid drives and the operation of hybrid vehicles are characteristic of contemporary automotive technology. Together with the electronic driver assistant systems, hybrid technology is of the greatest importance and both cannot be ignored by today's car drivers. This technical reference book provides the reader with a firsthand comprehensive description of significant components of automotive technology. All texts are complemented by numerous detailed illustrations.

This book examines the fundamentals of vehicle dynamics, as well as the recent trends in the field, such as torque vectoring control, vehicle state estimation, and autonomous vehicles. It investigates the most pressing problems that vehicle dynamics engineers have been facing nowadays, and the challenges of autonomous vehicles in terms of perception, path planning, and analysis of the road environment. The book will serve as a useful tool for graduate students and researchers in vehicle dynamics and control.

Semi-Active Suspension Control Design for Vehicles presents a comprehensive discussion of designing control algorithms for semi-active suspensions. It also covers performance analysis and control design. The book evaluates approaches to different control theories, and it includes methods needed for analyzing and evaluating suspension performances, while identifying optimal performance bounds. The structure of the book follows a classical path of control-system design; it discusses the actuator or the variable-damping shock absorber, models and technologies. It also models and discusses the vehicle that is equipped with semi-active dampers, and the control algorithms. The text can be viewed at three different levels: tutorial for novices and students; application-oriented for engineers and practitioners; and methodology-oriented for researchers. The book is divided into two parts. The first part includes chapters 2 to 6, in which fundamentals of modeling and semi-active control design are discussed. The second part includes chapters 6 to 8, which cover research-oriented solutions and case studies. The text is a comprehensive reference book for research engineers working on ground vehicle systems; automotive and design engineers working on suspension systems; control engineers; and graduate students in control theory and ground vehicle systems. Appropriate as a tutorial for students in automotive systems, an application-oriented reference for engineers, and a control design-oriented text for researchers that introduces semi-active suspension theory and practice.

Includes explanations of two innovative semi-active suspension strategies to enhance either comfort or road-holding performance, with complete analyses of both. Also features a case study showing complete implementation of all the presented strategies and summary descriptions of classical control algorithms for controlled dampers.

Revealing suspension geometry design methods in unique detail, John Dixon shows how suspension properties such as bump steer, roll steer, bump camber, compliance steer and roll centres are analysed and controlled by the professional engineer. He emphasizes the physical understanding of suspension parameters in three dimensions and methods of their calculation, using examples, programs and discussion of computational problems. The analytical and design approach taken is a combination of qualitative explanation, for physical understanding, with algebraic analysis of linear and non-linear coefficients, and detailed discussion of computer simulations and related programming methods. Includes a detailed and comprehensive history of suspension and steering system design, fully illustrated with a wealth of diagrams.

Explains suspension characteristics and suspension geometry coefficients, providing a unique
and in-depth understanding of suspension design not found elsewhere. Describes how to obtain desired coefficients and the limitations of particular suspension types, with essential information for suspension designers, chassis technicians and anyone else with an interest in suspension characteristics and vehicle dynamics. Discusses the use of computers in suspension geometry analysis, with programming techniques and examples of suspension solution, including advanced discussion of three-dimensional computational geometry applied to suspension design. Explains in detail the direct and iterative solutions of suspension geometry.

An updated edition of the classic reference on the dynamics of road and off-road vehicles. As we enter a new millennium, the vehicle industry faces greater challenges than ever before as it strives to meet the increasing demand for safer, environmentally friendlier, more energy efficient, and lower emissions products. Theory of Ground Vehicles, Third Edition gives aspiring and practicing engineers a fundamental understanding of the critical factors affecting the performance, handling, and ride essential to the development and design of ground vehicles that meet these requirements. As in previous editions, this book focuses on applying engineering principles to the analysis of vehicle behavior. A large number of practical examples and problems are included throughout to help readers bridge the gap between theory and practice. Covering a wide range of topics concerning the dynamics of road and off-road vehicles, this Third Edition is filled with up-to-date information, including: * The Magic Formula for characterizing pneumatic tire behavior from test data for vehicle handling simulations * Computer-aided methods for performance and design evaluation of off-road vehicles, based on the author's own research * Updated data on road vehicle transmissions and operating fuel economy * Fundamentals of road vehicle stability control * Optimization of the performance of four-wheel-drive off-road vehicles and experimental substantiation, based on the author's own investigations * A new theory on skid-steering of tracked vehicles, developed by the author.

Presenting the terminology of automotive engineering, this book introduces the basic mechanics and analytical methods used in vehicle dynamics. The text provides insight into tire force and torque generation and surveys the components of drive train and suspension systems. It also covers the fundamentals of vehicle dynamics and includes a tire model, as well as dynamic models of force elements. Using simple vehicle models, the author provides a deeper understanding of the dynamics of road vehicles. Many MATLAB® examples are used to verify theoretical predictions. Electronic lecture notes and a full solutions manual are available with qualifying course adoption.

"Road Vehicle Dynamics supplies students and technicians working in industry with both the theoretical background of mechanical and automotive engineering, and the know-how needed to perform numerical simulations. Bringing together the foundations of the discipline and its recent developments in a single text, the book is structured in three parts: it begins with a historical overview of road vehicles; then deals with the forces exchanged between the vehicle and the road, and the vehicle and the air; and finally, deals with the dynamic behavior of the vehicle in normal driving conditions with some extensions towards conditions encountered in high-speed racing. Coverage of contemporary automatic controls is included in this edition."--Publisher's website.

Featuring contributions from leading experts, the Road and Off-Road Vehicle System Dynamics Handbook provides comprehensive, authoritative coverage of all the major
issues involved in road vehicle dynamic behavior. While the focus is on automobiles, this book also highlights motorcycles, heavy commercial vehicles, and off-road vehicles. The authors examine in detail the fundamentals and mathematical descriptions of the dynamics of automobiles. In this context, different levels of complexity are presented, starting with basic single-track models up to complex three-dimensional multi-body models. A particular focus is on the process of establishing mathematical models based on real cars and the validation of simulation results. The methods presented are explained in detail by means of selected application scenarios. In addition to some corrections, further application examples for standard driving maneuvers have been added for the present second edition. To take account of the increased use of driving simulators, both in research, and in industrial applications, a new section on the conception, implementation and application of driving simulators has been added.

Road Vehicle Dynamics supplies students and technicians working in industry with both the theoretical background of mechanical and automotive engineering, and the know-how needed to perform numerical simulations. Bringing together the foundations of the discipline and its recent developments in a single text, the book is structured in three parts: it begins with a historical overview of road vehicles; then deals with the forces exchanged between the vehicle and the road, and the vehicle and the air; and finally, deals with the dynamic behavior of the vehicle in normal driving conditions with some extensions towards conditions encountered in high-speed racing. Coverage of contemporary automatic controls is included in this edition.

In striving for optimal comfort and safety conditions in road vehicles, today’s electronically controlled components provide a range of new options. These are developed and tested using computer simulations in software in the loop or hardware in the loop environments—an advancement that requires the modern automotive engineer to be able to build basic simulation models, handle higher level models, and operate simulation tools effectively. Combining the fundamentals of vehicle dynamics with the basics of computer simulated modeling, Road Vehicle Dynamics: Fundamentals and Modeling Aspects draws on lecture notes from undergraduate and graduate courses given by the author, as well as industry seminars and symposiums, to provide practical insight on the subject. Requiring only a first course in dynamics and programming language as a prerequisite, this highly accessible book offers end-of-chapter exercises to reinforce concepts as well as programming examples and results using MATLAB®. The book uses SI-units throughout, and begins with an introduction and overview of units and quantities, terminology and definitions, multibody dynamics, and equations of motion. It then discusses the road, highlighting both deterministic and stochastic road models; tire handling including contact calculation, longitudinal and lateral forces, vertical axis torques, and measurement and modeling techniques; and drive train components and concepts such as transmission, clutch, and power source. Later chapters discuss suspension systems, including a dynamic model of rack-and-pinion steering as well as double-wishbone suspension systems; force elements such as springs, anti-roll bars, and hydro-mounts; and vehicle dynamics in vertical, longitudinal, and lateral directions using a simple model approach to examine the effects of nonlinear, dynamic, and active force elements. Highlighting useable knowledge, the book concludes with a three-dimensional vehicle model and typical results of standard
The broad aim of this text is to provide a comprehensive coverage of the modelling and optimal control of both two- and four-wheeled road vehicles. The first focus of the work is a review of classical mechanics and its use in building vehicle and tyre dynamic models. The second is nonlinear optimal control, which is used to solve a range of minimum-time, minimum-fuel, and track curvature reconstruction problems.

The definitive book on tire mechanics by the acknowledged world expert Covers everything you need to know about pneumatic tires and their impact on vehicle performance, including mathematic modeling and its practical application. Written by the acknowledged world authority on the topic and the name behind the most widely used model, Pacejka’s ‘Magic Formula’ Updated with the latest information on new and evolving tire models to ensure you can select the right model for your needs, apply it appropriately and understand its limitations. In this well-known resource, leading tire model expert Hans Pacejka explains the relationship between operational variables, vehicle variables and tire modeling, taking you on a journey through the effective modeling of complex tire and vehicle dynamics problems. Covering the latest developments to Pacejka’s own industry-leading model as well as the widely-used models of other pioneers in the field, the book combines theory, guidance, discussion and insight in one comprehensive reference. While the details of individual tire models are available in technical papers published by SAE, FISITA and other automotive organizations, Tire and Vehicle Dynamics remains the only reliable collection of information on the topic and the standard go-to resource for any engineer or researcher working in the area. New edition of the definitive book on tire mechanics, by the acknowledged world authority on the topic Covers everything an automotive engineer needs to know about pneumatic tires and their impact on vehicle performance, including mathematic modelling and its practical application. Most vehicle manufacturers use what is commonly known as Pacejka’s ‘Magic Formula’, the tire model developed and presented in this book.

Provides a detailed overview of the dynamics of road vehicle systems, giving readers an understanding of how physical laws, human factor considerations, and design choices affect ride, handling, braking, acceleration, and vehicle safety. Chapters cover analysis of dynamic systems, tyre dynamics, ride dynamics, vehicle rollover analysis, handling dynamics, braking, acceleration, total vehicle dynamics, and accident reconstruction.

Essentials of Vehicle Dynamics explains the essential mathematical basis of vehicle dynamics in a concise and clear way, providing engineers and students with the qualitative understanding of vehicle handling performance needed to underpin chassis-related research and development. Without a sound understanding of the mathematical tools and principles underlying the complex models in vehicle dynamics, engineers can end up with errors in their analyses and assumptions, leading to costly mistakes in design and virtual prototyping activities. Author Joop P. Pauwelussen looks to rectify this by drawing on his 15 years’ experience of helping students and professionals understand the vehicle as a dynamic system. He begins as simply as possible before moving on to tackle models of increasing complexity, emphasizing the critical role played by tire-road contact and the different analysis tools required to consider non-
linear dynamical systems. Providing a basic mathematical background that is ideal for
students or those with practical experience who are struggling with the theory,
Essentials of Vehicle Dynamics is also intended to help engineers from different
disciplines, such as control and electronic engineering, move into the automotive sector
or undertake multi-disciplinary vehicle dynamics work. Focuses on the underlying
mathematical fundamentals of vehicle dynamics, equipping engineers and students to
grasp and apply more complex concepts with ease. Written to help engineers avoid the
costly errors in design and simulation brought about by incomplete understanding of
modeling tools and approaches. Includes exercises to help readers test their qualitative
understanding and explain results in physical and vehicle dynamics terms.
In spite of all the assistance offered by electronic control systems, the latest
generation of passenger car chassis still relies on conventional chassis elements.
With a view towards driving dynamics, this book examines these conventional
elements and their interaction with mechatronic systems. First, it describes the
fundamentals and design of the chassis and goes on to examine driving
dynamics with a particularly practical focus. This is followed by a detailed
description and explanation of the modern components. A separate section is
devoted to the axles and processes for axle development. With its revised
illustrations and several updates in the text and list of references, this new edition
already includes a number of improvements over the first edition.
This book attempts to find a middle ground by balancing engineering principles
and equations of use to every automotive engineer with practical explanations of
the mechanics involved, so that those without a formal engineering degree can
still comprehend and use most of the principles discussed. Either as an
introductory text or a practical professional overview, this book is an ideal
reference.
Vehicle Dynamics and Control: Advanced Methodologies features the latest
information on advanced dynamics and vehicle motion control, including a
comprehensive overview of passenger cars and articulated vehicles,
fundamentals, and emerging developments. This book provides a unified,
balanced treatment of advanced approaches to vehicle dynamics and control. It
proceeds to cover advanced vehicle control strategies, such as identification and
estimation, adaptive nonlinear control, new robust control techniques, and soft
computing. Other topics, such as the integrated control of passenger cars and
articulated heavy vehicles, are also discussed with a significant amount of
material on engineering methodology, simulation, modeling, and mathematical
verification of the systems. This book discusses and solves new challenges in
vehicle dynamics and control problems and helps graduate students in the field
of automotive engineering as well as researchers and engineers seeking
theoretical/practical design procedures in automotive control systems. Provides a
vast spectrum of advanced vehicle dynamics and control systems topics and
current research trends Provides an extensive discussion in some advanced
topics on commercial vehicles, such as dynamics and control of semitrailer
carrying liquid, integrated control system design, path planning and tracking control in the autonomous articulated vehicle

This volume contains the proceedings of the 2000 International Congress of Theoretical and Applied Mechanics. The book captures a snapshot view of the state of the art in the field of mechanics and will be invaluable to engineers and scientists from a variety of disciplines.

A comprehensive overview of integrated vehicle system dynamics exploring the fundamentals and new and emerging developments This book provides a comprehensive coverage of vehicle system dynamics and control, particularly in the area of integrated vehicle dynamics control. The book consists of two parts, (1) development of individual vehicle system dynamic model and control methodology; and (2) development of integrated vehicle dynamic model and control methodology. The first part focuses on investigating vehicle system dynamics and control according to the three directions of vehicle motions, including longitudinal, vertical, and lateral. Corresponding individual control systems, e.g. Anti-lock Brake System (ABS), Active Suspension, Electric Power Steering System (EPS), are introduced and developed respectively. Particular attention is paid in the second part of the book to develop integrated vehicle dynamic control system. Integrated vehicle dynamics control system is an advanced system that coordinates all the chassis control systems and components to improve the overall vehicle performance including safety, comfort, and economy. Integrated vehicle dynamics control has been an important research topic in the area of vehicle dynamics and control over the past two decades. The research topic on integrated vehicle dynamics control is investigated comprehensively and intensively in the book through both theoretical analysis and experimental study. In this part, two types of control architectures, i.e. centralized and multi-layer, have been developed and compared to demonstrate their advantages and disadvantages. Integrated vehicle dynamics control is a hot topic in automotive research; this is one of the few books to address both theory and practice of integrated systems Comprehensively explores the research area of integrated vehicle dynamics and control through both theoretical analysis and experimental study Addresses a full range of vehicle system topics including tyre dynamics, chassis systems, control architecture, 4 wheel steering system and design of control systems using Linear Matrix Inequality (LMI) Method

This book on the dynamics of rail vehicles is developed from the manuscripts for a class with the same name at TU Berlin. It is directed mainly to master students with pre-knowledge in mathematics and mechanics and engineers that want to learn more. The important phenomena of the running behaviour of rail vehicles are derived and explained. Also recent research results and experience from the operation of rail vehicles are included. One focus is the description of the complex wheel-rail contact phenomena that are essential to understand the concept of running stability and curving. A reader should in the end be able to
understand the background of simulation tools that are used by the railway industry and universities today.

Vehicle Dynamics and Control provides a comprehensive coverage of vehicle control systems and the dynamic models used in the development of these control systems. The control system applications covered in the book include cruise control, adaptive cruise control, ABS, automated lane keeping, automated highway systems, yaw stability control, engine control, passive, active and semi-active suspensions, tire-road friction coefficient estimation, rollover prevention, and hybrid electric vehicles. In developing the dynamic model for each application, an effort is made to both keep the model simple enough for control system design but at the same time rich enough to capture the essential features of the dynamics. A special effort has been made to explain the several different tire models commonly used in literature and to interpret them physically. In the second edition of the book, chapters on roll dynamics, rollover prevention and hybrid electric vehicles have been added, and the chapter on electronic stability control has been enhanced. The use of feedback control systems on automobiles is growing rapidly. This book is intended to serve as a useful resource to researchers who work on the development of such control systems, both in the automotive industry and at universities. The book can also serve as a textbook for a graduate level course on Vehicle Dynamics and Control.

Hardbound. The computer-aided methods presented in this book represent recent advances in the methodology for predicting and evaluating off-road vehicle performance. The mathematical models established for vehicle-terrain systems will enable the engineering practitioner to evaluate, on a rational basis, a wide range of options and to select an appropriate vehicle configuration for a given mission and environment. The models take into account all major design and operational parameters, as well as pertinent terrain characteristics. Applications of the computer-aided engineering methods to the parametric analysis of off-road vehicle design are demonstrated through examples.

This textbook is appropriate for senior undergraduate and first year graduate students in mechanical and automotive engineering. The contents in this book are presented at a theoretical-practical level. It explains vehicle dynamics concepts in detail, concentrating on their practical use. Related theorems and formal proofs are provided, as are real-life applications. Students, researchers and practicing engineers alike will appreciate the user-friendly presentation of a wealth of topics, most notably steering, handling, ride, and related components. This book also: Illustrates all key concepts with examples Includes exercises for each chapter Covers front, rear, and four wheel steering systems, as well as the advantages and disadvantages of different steering schemes Includes an emphasis on design throughout the text, which provides a practical, hands-on approach

Performance Vehicle Dynamics: Engineering and Applications offers an accessible treatment of the complex material needed to achieve level seven learning outcomes in the field. Users will gain a complete, structured understanding that enables the preparation of useful models for characterization and optimization of performance using
the same Automotive or Motorsport industry techniques and approaches. As the approach to vehicle dynamics has changed over time, largely due to advances in computing power, the subject has, in practice, always been computer intensive, but this use has changed, with modeling of relatively complex vehicle dynamics topics now even possible on a PC. Explains how to numerically and computationally model vehicle dynamics Features the use of cost functions with multi-body models Learn how to produce mathematical models that offer excellent performance prediction

Road Vehicle Dynamics: Fundamentals and Modeling with MATLAB®, Second Edition combines coverage of vehicle dynamics concepts with MATLAB v9.4 programming routines and results, along with examples and numerous chapter exercises. Improved and updated, the revised text offers new coverage of active safety systems, rear wheel steering, race car suspension systems, airsprings, four-wheel drive, mechatronics, and other topics. Based on the lead author's extensive lectures, classes, and research activities, this unique text provides readers with insights into the computer-based modeling of automobiles and other ground vehicles. Instructor resources, including problem solutions, are available from the publisher.

This textbook covers handling and performance of both road and race cars. Mathematical models of vehicles are developed always paying attention to state the relevant assumptions and to provide explanations for each step. This innovative approach provides a deep, yet simple, analysis of the dynamics of vehicles. The reader will soon achieve a clear understanding of the subject, which will be of great help both in dealing with the challenges of designing and testing new vehicles and in tackling new
research topics. The book deals with several relevant topics in vehicle dynamics that are not discussed elsewhere and this new edition includes thoroughly revised chapters, with new developments, and many worked exercises. Praise for the previous edition:

Great book! It has changed drastically our approach on many topics. We are now using part of its theory on a daily basis to constantly improve ride and handling performances.
--- Antonino Pizzuto, Head of Chassis Development Group at Hyundai Motor Europe Technical Center

Astonishingly good! Everything is described in a very compelling and complete way. Some parts use a different approach than other books.
--- Andrea Quintarelli, Automotive Engineer

The 18th Symposium of the International Association for Vehicle System Dynamics was held at Kanagawa Institute of Technology, Atsugi, Kanagawa, Japan. The symposium was hosted by KAIT as one of the memorial events of the 40th anniversary of KAIT. Though overwhelming numbers of high quality papers were applied in response to the call for papers for the presentation at the symposium, the Scientific Committee accepted 89 papers for the oral presentation and 38 for the poster presentation. Finally, 82 papers were presented at the oral sessions and 29 papers at the poster sessions in the symposium. There were five States-of-the-Arts papers presented at the plenary sessions in the symposium.

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